

# Where we are in the process:

- Find a reasonable “usage case” – assume technology will continue to improve, cost will come down.
- Find a **User** and think about what she or he needs
- Thursday: quick update from each team on how things are progressing
- Before 25 March: schedule individual meeting with each team

# benchmarking: technology + users

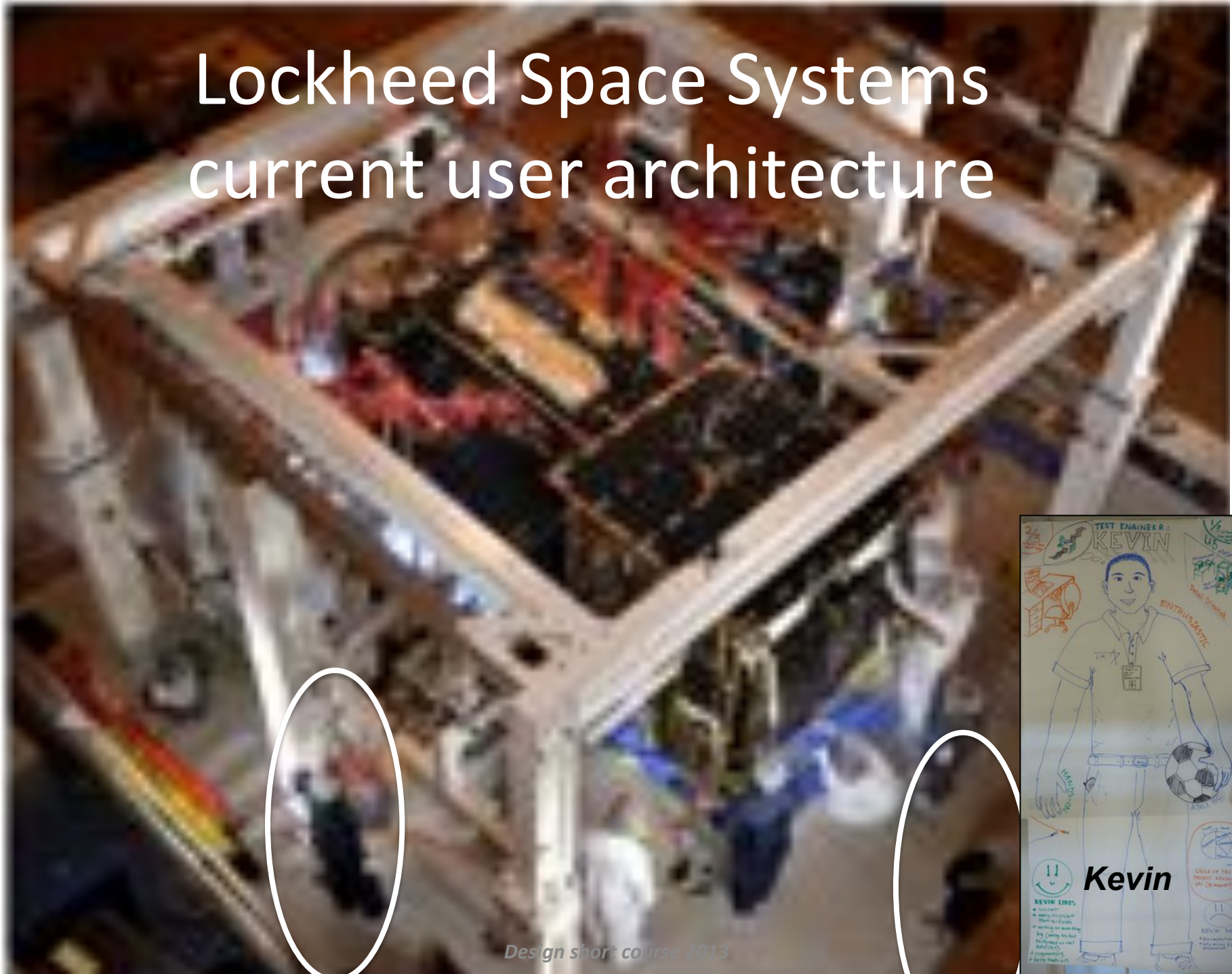


*Design short course 2013*

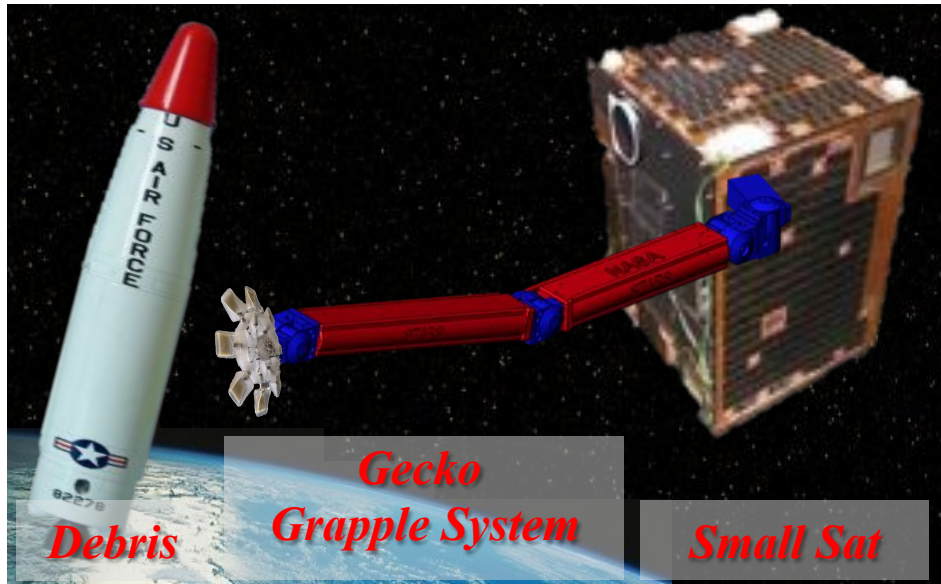




# Lockheed Space Systems current user architecture



# Gecko-Inspired ON-OFF Adhesives For Orbital Debris Mitigation



## Task Objectives:

1. Develop full capture head using current gecko adhesive and leveraging small-scale two pad gripper prototypes
2. Mock up compliant robotic arm and integrate with capture head for floating object capture demonstration on RoboDome testbed

## Infusion Path:

- option A: Small Sat Demo (partner with Qinetiq and Aerospace Corp)
- option B: ISS experiment or inspection (partner with JSC)

## Technical Approach / Expected Accomplishment:

**Develop Robotic Capture Head**

**Mock up compliant robotic arm**

**Demo floating object capture**

Role	Team Members	Section
PI	Aaron Parness	347
Co-I	Mark Cutkosky	Stanford
Co-I	George Studor	JSC
Co-I	Victor White	389
Co-I	Carl Seubert	344

Critical Milestones	Date
Demo of capture head on stiff mount	Apr 2013
Completion of mock-up compliant arm	Jun 2013
Demo of floating object capture	Sep 2013

## Primary Technical Hurdles:

- **Scaling 2-pad prototypes to full capture head**
- **Correctly sizing compliance in robotic arm**
  - **Integrating elements for demo**





meet Kevin  
(Aaron)



[https://www-robotics.jpl.nasa.gov/people/Aaron\\_Parness/](https://www-robotics.jpl.nasa.gov/people/Aaron_Parness/)

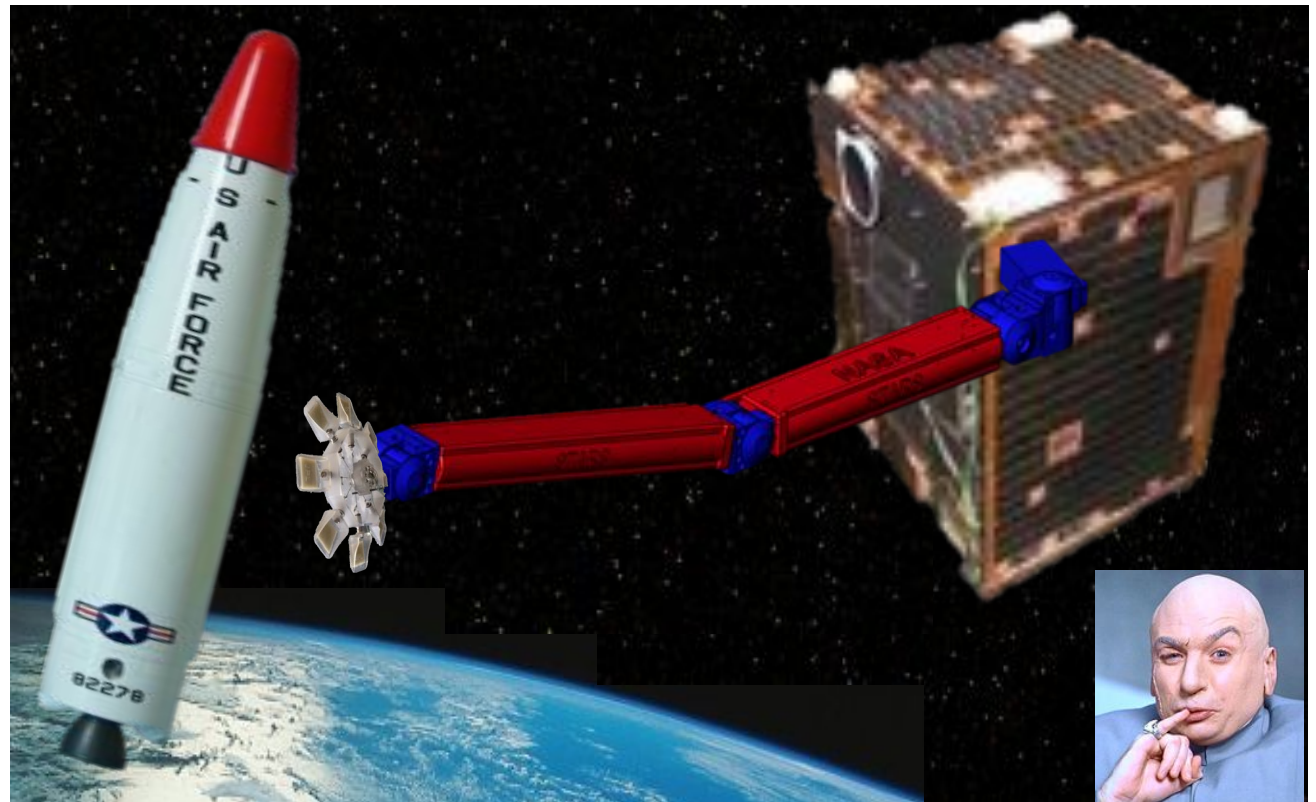
***what does Aaron want or need?***

# *Make it work for Aaron*

Aaron will be on the ground, controlling a robot in space to acquire dangerous space debris – ideally in way that some components can be recycled.

*Decompose Aaron's requirements. The best way to do this is to imagine the process he will need to follow in some detail:*

- **locate** space junk
- **contact** surface
- **align** to surface
- **attach** to surface
- **retrieve** space junk
- **store** onboard host satellite



# What does Aaron want or need?

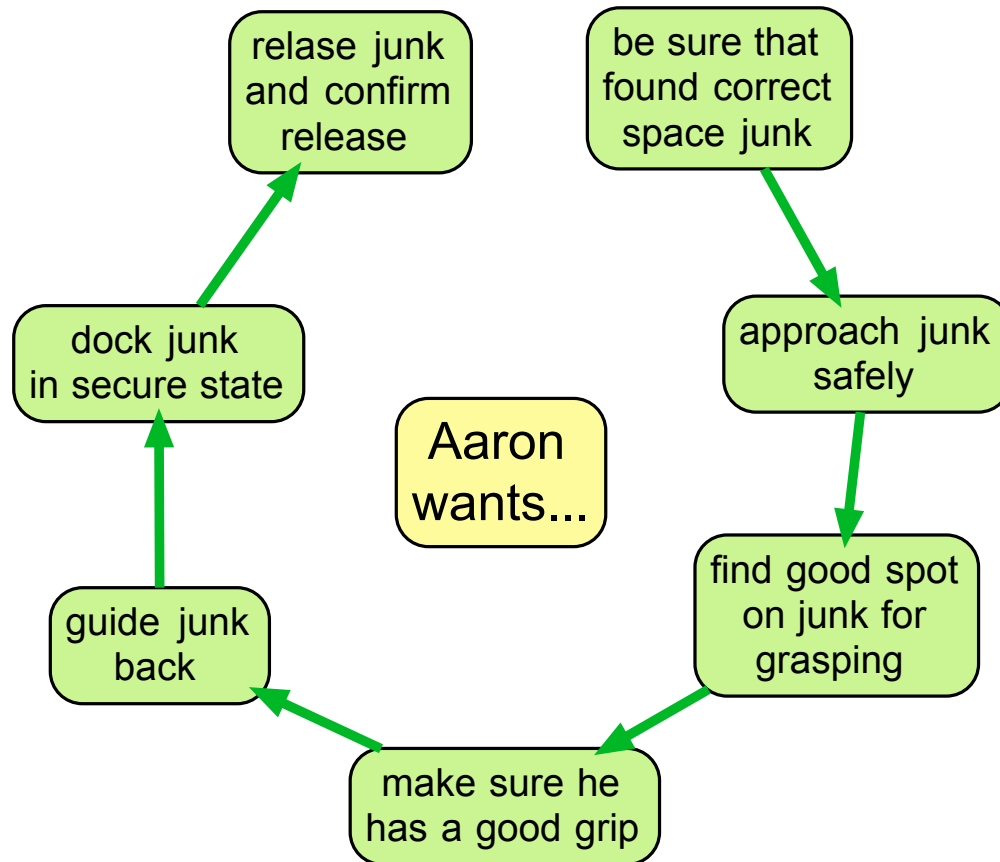


Aaron  
wants...

*User-centered:  
start with person,  
not with stuff!*

# What does Aaron want or need?

Tasks: → functional requirements

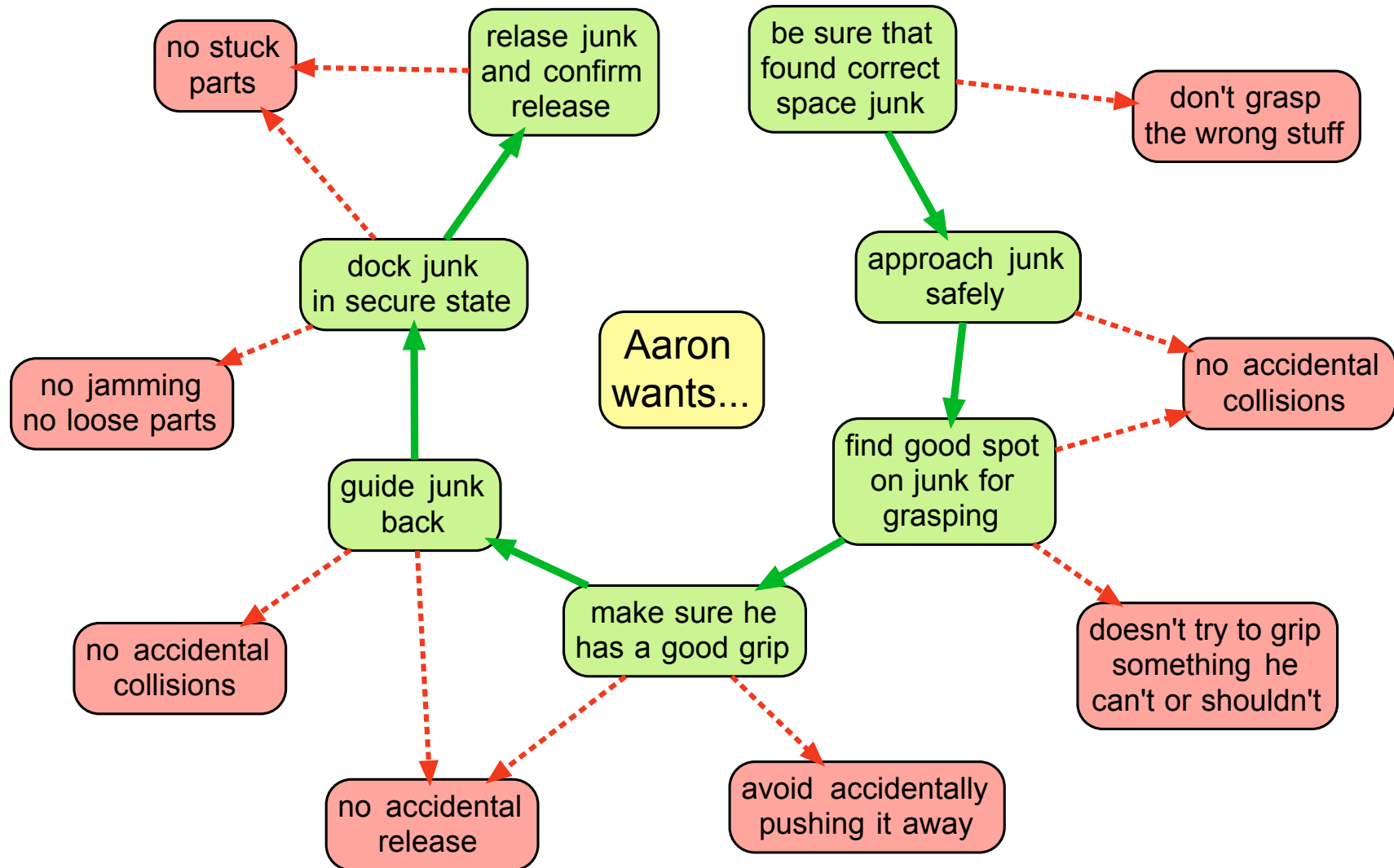


**Graph built using VUE: free graphing tool from Tufts University ( <http://vue.tufts.edu/> )**



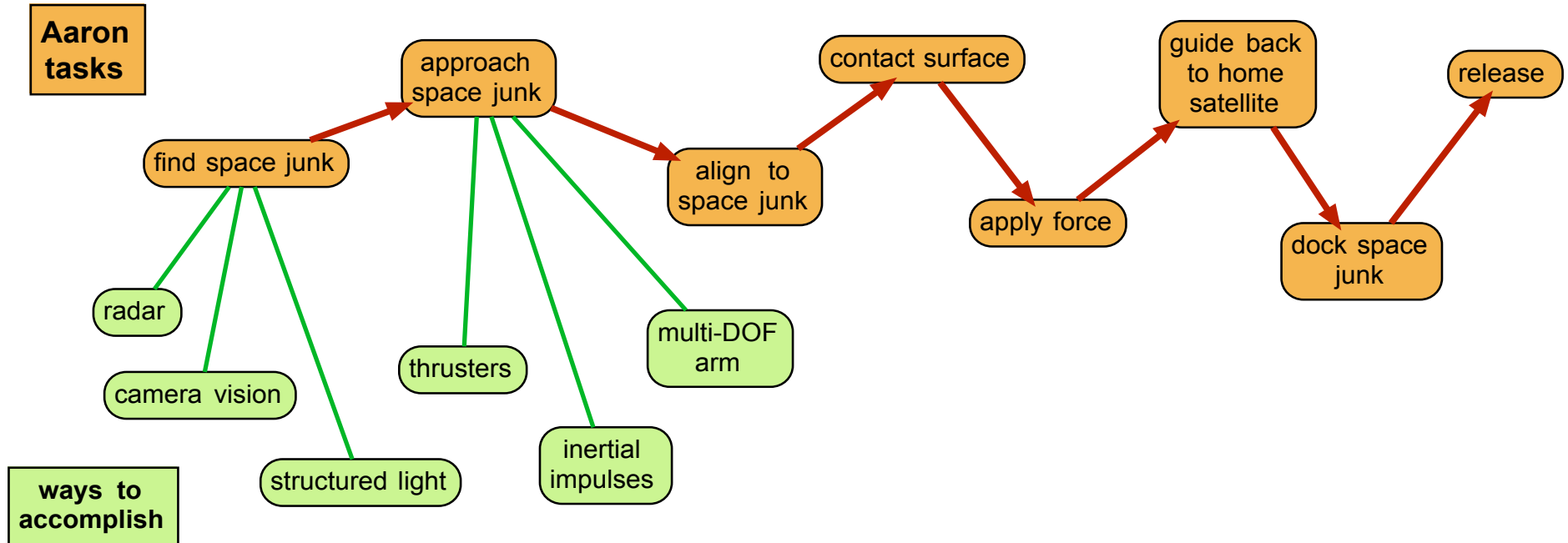
# What does Aaron want or need?

Identify failure modes → need for systems or sensing



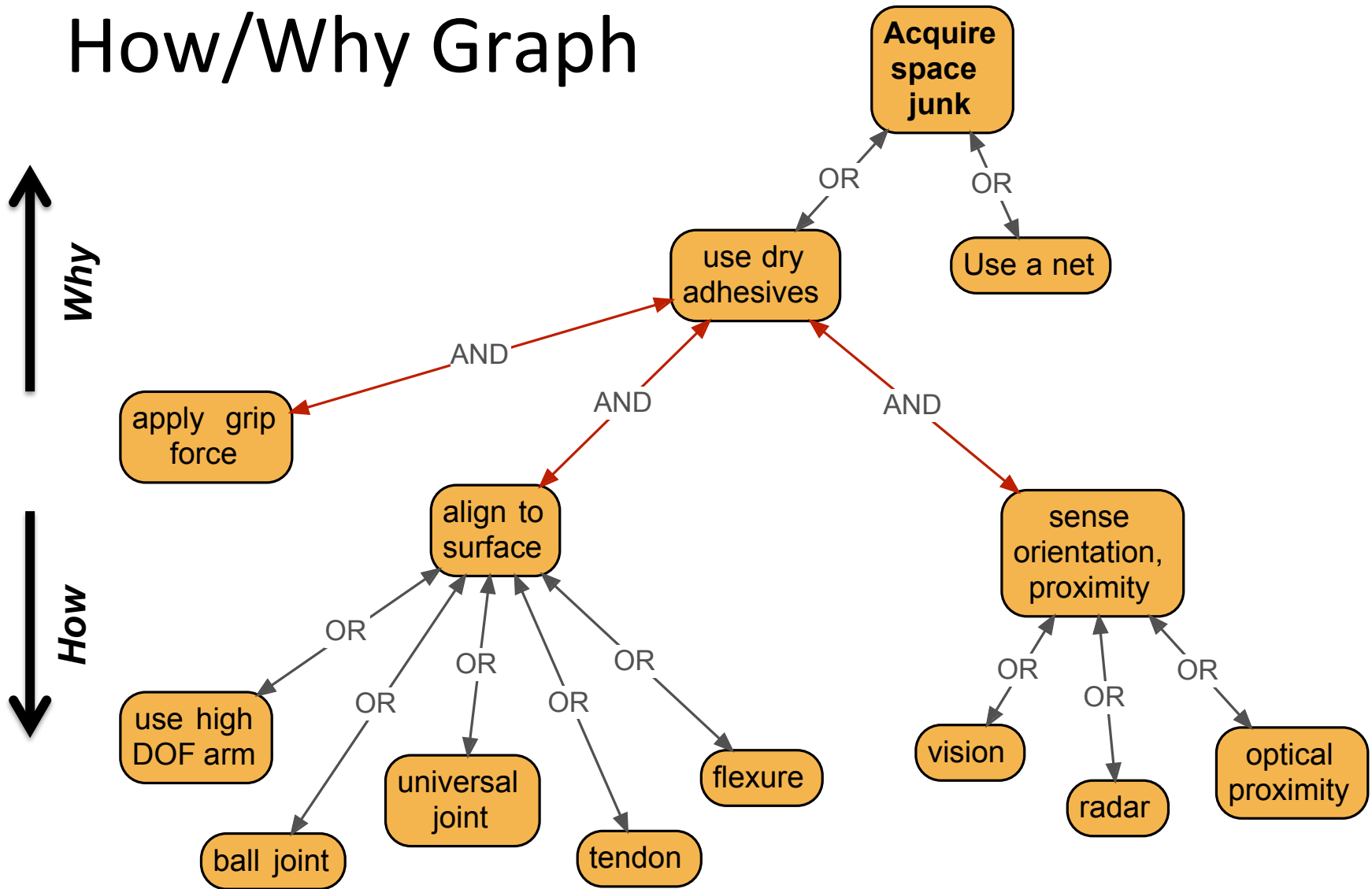
Graph built using VUE: free graphing tool from Tufts University ( <http://vue.tufts.edu/> )

# Mapping from **tasks**, or **functions**, to **systems**, or **structures**



*Graph built using VUE: free graphing tool from  
Tufts University ( <http://vue.tufts.edu/> )*

# How/Why Graph



Graph built using VUE: free graphing tool from Tufts University ( <http://vue.tufts.edu/> )



Once user needs are defined, we pick a  
“**critical**” one for prototyping...



## For now:

- Spend some time with your group articulating user needs (functional) and ways to achieve (systems)
- Draw on large sheets paper and/or use a tool like VUE if you like.
- Meanwhile... Cutkosky starts some individual group meetings
- For Thursday: Each team should provide a short update what they have discovered